Template No. CEMILAC_ACGP_CMALW_03

Compliance Matrix for Air Launched Weapon

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Disclaimer:

This document is a guidance document. Applicable section / table rows may be considered. Any additional details may be added. Any not applicable section/ table rows may be deleted. The template is very general and vary with process to process followed by Development Agency. The document may be fine-tuned with the TAA for finalization.

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Compliance Checklist for Air Launched Weapons

System Level

SI.No.	Activity/ Document	Compliance	Remarks
1	CONOPS		
2	System Safety Analysis/ Functional Hazard Analysis		
3	Product Breakdown Structure		
4	Functional/ System Requirement Document		
5	Test Requirement Traceability Matrix		
6	Inter-operability with co-located systems		
7	Test rigs and Simulators availability		

Product Breakdown Structure

SI.No	Subsystem N	ame & Part Number :	Software		Firmware/ FPGA		IP Cores			
	Design agency	Realisation/ development agency	Govt QA agency	Part No.	Design agency	IV&V agency	Design agency	IV&V agency	Design agency	IV&V agency

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Functional Hazard Analysis :

- a. Decomposition of the system and its related subsystems to the major component level.
- b. A functional description of each subsystem and component identified.
- c. A functional description of interfaces between subsystems and components. Interfaces should be assessed in terms of connectivity and functional inputs and outputs.
- d. Hazards associated with loss of function, degraded function or malfunction, or functioning out of time or out of sequence for the subsystems, components, and interfaces. The list of hazards should consider the next effect in a possible mishap sequence and the final mishap outcome.
- e. An assessment of the risk associated with each identified failure of a function, subsystem, or component. Estimate severity, probability, and Risk Assessment Code (RAC)
- f. An assessment of whether the functions identified are to be implemented in the design hardware, software, or human control interfaces. This assessment should map the functions to their implementing hardware or software components. Functions allocated to software should be mapped to the lowest level of technical design or configuration item prior to coding (e.g., implementing modules or use cases).
- g. An assessment of Software Control Category (SCC) for each Safety-significant Software Function (SSSF). Assign a Software Criticality Index (SwCI) for each SSSF mapped to the software design architecture.
- h. A list of requirements and constraints (to be included in the specifications) that, when successfully implemented, will eliminate the hazard or reduce the risk. These requirements could be in the form of fault tolerance, detection, isolation, annunciation, or recovery.

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SI.No	ID	Function	Hazard	Hazard	Final mishap/	Severity	Probability	Risk	Implemented	SwCI/ HwCI	Mitigation
				Consequence	outcome			Assessment	in		Requirements
								Code (RAC)			
1											
2											
3											

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Test Requirement Traceability Matrix

					Means	of Complia	nce					
	Requirement	Review	Analysis	Simulation	Equivalence	Product History	La le	ab evel est	Rig / Aircraft level test	Flight test	Other	Compliance status
	Dimensions											
	Weight											
	Installation											
	Grounding/ shielding/Bonding											
cal	Marking											
Physical	Materials											
占	Power Consumption											
Environmental	Vibration i) Sinusoidal ii) Platform specific iii) Buffet High Temperature i) Storage ii) Operation Low Temperature i) Storage ii) Operation Shock Acceleration i) Structural											
Envi	ii) Functional CATH											
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Humidity						
Altitude						
Fungus						
Rain drip						
Immersion						
Salt fog						
Sand and dust						
Solar radiation						
Acoustic Vibration						
Pyroshock						
Transit drop						
Safety Drop						
Service Drop						
Bench handling						
Tropical Exposure						
Air Exposure						
Bump						
Gun fire vibration						
Hail impact						
Blowing rain						
Fast Cook Off						
Slow Cook Off						
Bullet Impact						
Fragment Impact						
Sympathetic						
Detonation						
Distortion spectru	m					
measurements						

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	Power interruption					
	(50 ms)					
	Emergency					
	Operation (16V)					
	Engine ON					
	operation (12V)					
	Polarity reversal					
	Normal steady state					
	Abnormal steady					
	state					
	Normal transients					
	Abnormal transients					
	RE101					
	RE102					
	RE103					
	CE101					
	CE102					
	CE106					
	CS101					
	CS103					
	CS104					
	CS105					
	CS109					
	CS114					
U	CS115					
EMI/EMC	CS116					
٦F	CS117 (ESD)					
Ш	CS118 (Lightning)					

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Parameter!	5											
Parameter	3											
Parameter	2											
Parameter:	1											
Spec1												
External int	orfaco1											
Hardware l	n Loop											
Pit Drop												
Flutter Ana	lysis											
GVT												
HERO												
RS105												
RS101 RS103 (xyz	V/m)											
	RS103 (xyz RS105 HERO GVT Flutter Ana Pit Drop Wind Tunn Structural L Phase Chec Sign Checks Sensor In La Hardware I External int External int External int External int Spec1 Spec2 Spec3 Parameter Parameter	RS103 (xyz V/m) RS105 HERO GVT Flutter Analysis Pit Drop Wind Tunnel Structural Load Phase Checks Sign Checks Sensor In Loop Hardware In Loop Hardware In Loop External interface1 External interface2 External interface3 Spec1 Spec2 Spec3 Parameter1 Parameter2 Parameter3 Parameter4 Parameter5	RS103 (xyz V/m)RS105HEROGVTFlutter AnalysisPit DropWind TunnelStructural LoadPhase ChecksSign ChecksSensor In LoopHardware In LoopExternal interface1External interface2External interface3Spec1Spec2Spec3Parameter1Parameter2Parameter3Parameter4Parameter5	RS103 (xyz V/m)RS105RS105Image: State of the	RS103 (xyz V/m)RS105RS105Image: Constraint of the sector of th	RS103 (xyz V/m)RS105HEROGVTGVTFlutter AnalysisPit DropWind TunnelWind TunnelStructural LoadPhase ChecksSign ChecksSign ChecksSensor In LoopHardware In LoopSteternal interface1External interface2Spec1Spec3Spec3Parameter1Parameter2Parameter4SpeakParameter4SpeakParameter4SpeakParameter4SpeakParameter5Speak	RS103 (xyz V/m) RS105 HERO GVT Flutter Analysis Pit Drop Wind Tunnel Structural Load Phase Checks Sign Checks Sensor In Loop Hardware In Loop External interface1 External interface2 External interface3 Spec1 Spec3 Parameter1 Parameter3 Parameter4 Parameter4	RS103 (xyz V/m)	RS103 (xyz V/m)	RS103 (xyz V/m)	R\$103 (xyz V/m)	R\$103 (xyz V/m) Image: state in the s

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	Maintenance					
	requirement					
	(Calibration,					
	requirement (Calibration, pressurisation etc)					
	Technical Life					
	Calendar Life					

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<u>Software</u>

SI No	Activity/ Artefact	Doc/Report avl?	IV&V Observations avl?	Observations closed?	Remarks
1	Software Certification Plan				
2	Software Requirement Document				
3	Software Requirement Review				
4	Software Design Document				
5	Software Design Review				
6	Algorithm Validation				
7	Source Code				
8	Code walkthrough report				
9	Software HSI level Test cases				
10	Integration level test cases				
11	HILS test cases				
12	Bidirectional Traceability Matrix				
13	Static Analysis (memory, stack, bus				
	load, coding standard)				
14	Dynamic analysis (WCET, timing,				
	coverage, exception handling)				
15	Software Test Reports				
16	Version Description Document				
17	IV & V recommendations		NA	NA	
18	SPR, SCR, SCN				
19	Test rig Software				

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<u>FPGA</u>

SI No	Activity/ Artefact	Doc/Report avl?	IV&V Observations avl?	Observations closed?	Remarks
1	Hardware Certification Plan				
2	Hardware Requirement Document				
3	Hardware Requirement Review				
4	Hierarchical schematics, Block				
	diagrams, Floor planning				
5	Hardware Design Review				
6	Algorithm Validation				
7	VHDL Code, RTL code, Finite State				
	machine				
8	Code walkthrough report				
9	In-circuit test cases				
10	Netlist, Synthesis report, Place and				
	Route report				
11	Elemental analysis/ Code coverage				
12	Timing and clock skew analysis,				
	Logic analysis, resource analysis				
13	Functional failure path analysis,				
	common mode failure analysis				
14	Pin details with signal mapping				
15	In target at speed Test Report				
16	IV&V recommendations		NA	NA	
17	Version Description Document				
18	PRs and CNs				
19	Test rig software				

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Limitations:

SI.No	Limitation/ Observation/Deviation	Operational and/or safety Implications of the limitation	Mitigation Plan	PDC for implementation of mitigation

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